

6th
UCAAT

User Conference on
Advanced Automated Testing



Paris, 16-18 October 2018



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Diagnosis of V2X communication via evaluation modules and textual rule sets
Presented by Tim Ruß

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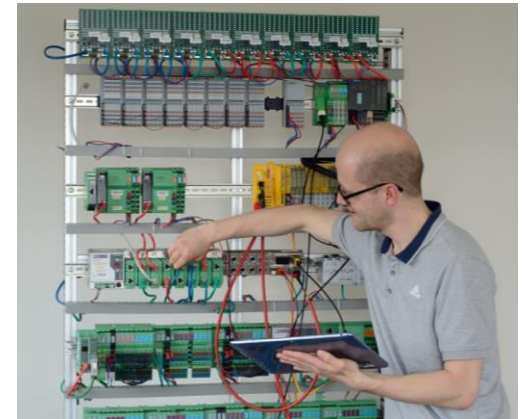


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Motivation

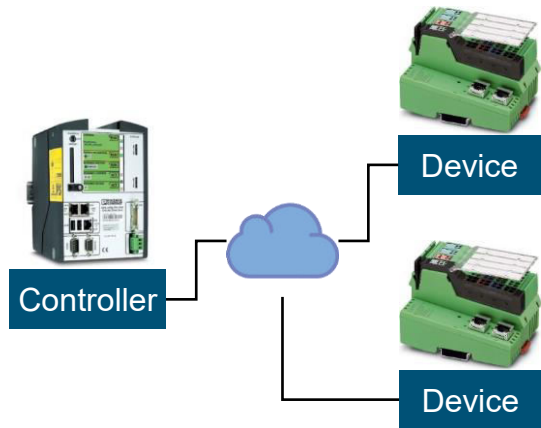
ifak: Institute for Automation and Communication

- Applied research
- Test laboratories

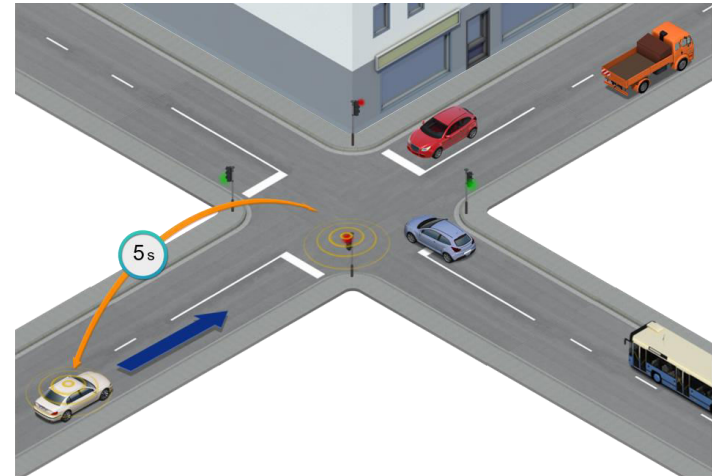


Examples for our communication domains

Factory Automation



Vehicle-to-X (also: Car2X)



Manual process: Checking Wireshark records

- Search for connection / startup sequence
- Search for errors (alarms, connection releases...)

→ Demand to automate such processes

No.	Time	Info
5	2.627070	Ident Req, Xid:0x6a006b, AliasName:"port-001.rfc-470-rus-iod"
6	4.204942	Ident Req, Xid:0x6b006c, NameOfStation:"rfc-470-rus-iod"
7	4.258338	Ident Ok , Xid:0x6b006c, NameOfStation:"rfc-470-rus-iod", Dev-Opti
8	5.139583	TTL = 20 RTClass3 Port Status = OFF
9	5.317040	Who has 172.16.47.36? Tell 172.16.47.32
10	5.342206	172.16.47.36 is at 00:a0:45:51:1e:bf
11	5.507997	TTL = 20 RTClass3 Port Status = OFF
12	5.534469	Dropbox LAN sync Discovery Protocol
13	5.534636	Dropbox LAN sync Discovery Protocol
14	7.460534	Connect request, ARBlockReq, IOCRBlockReq, IOCRBlockReq, ExpectedS
15	7.566681	Connect response, OK, ARBlockRes, IOCRBlockRes, IOCRBlockRes, Alar
16	7.597427	RTC1, ID:0x9000, Len: 515, Cycle:28640 (Valid,Primary,Ok,Run)
17	7.665373	RTC1(legacy), ID:0xd000, Len: 515, Cycle:24544 (Valid,Primary,Ok,R
18	7.676836	Control request, IODControlReq Prm End.req, Command: ParameterEnd
19	7.722487	RTC1, ID:0x9000, Len: 515, Cycle:32736 (Valid,Primary,Ok,Run)
20	7.752361	Control response, OK, IODControlRes Prm End.rsp, Command: Done
21	7.783395	Control request, IOXBlockReq Application Ready.req, Command: Appli
22	7.793132	RTC1(legacy), ID:0xd000, Len: 515, Cycle:28640 (Valid,Primary,Ok,R
23	7.820737	Control response, OK, IOXBlockRes Application Ready.rsp, Command:
24	7.846338	RTC1, ID:0x9000, Len: 515, Cycle:36832 (Valid,Primary,Ok,Run)
25	7.920719	RTC1(legacy), ID:0xd000, Len: 515, Cycle:32736 (Valid,Primary,Ok,R
26	7.970069	RTC1, ID:0x9000, Len: 515, Cycle:40928 (Valid,Primary,Ok,Run)
27	7.992075	Read request, IODReadReqHeader, Api:0x0, Slot:0x0/0x0, Index:PDR
28	8.046153	Read response, OK, IODReadResHeader, Api:0x0, Slot:0x0/0x0, Index:
29	8.048382	RTC1(legacy), ID:0xd000, Len: 515, Cycle:36832 (Valid,Primary,Ok,R

Agenda

- Scope and methods
- Approach
- Use case
- Summary

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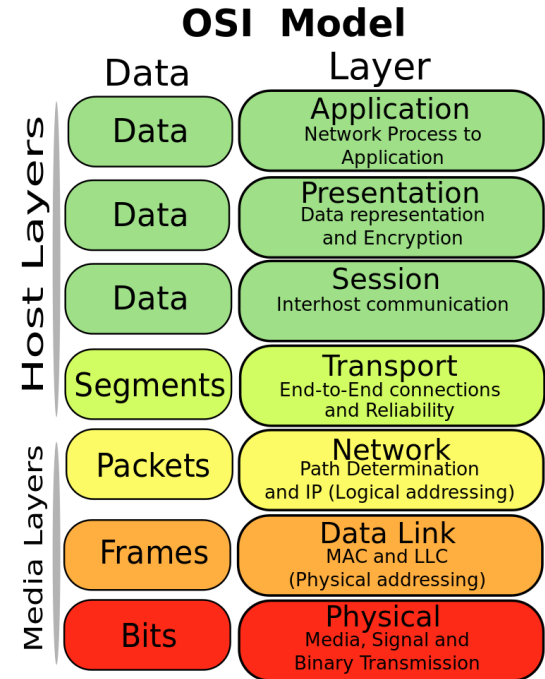


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Scope and methods

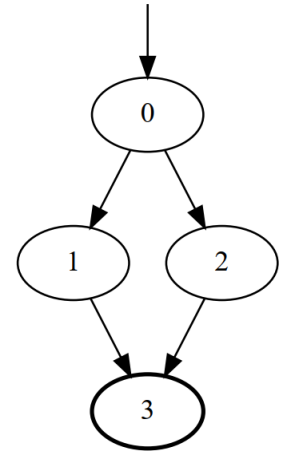
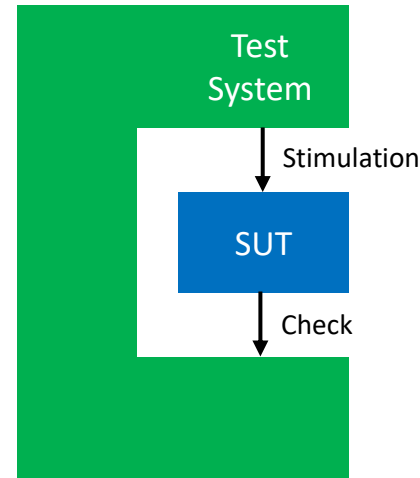
Scope and terminology

- Network communication of distributed (computer) systems:
 - OSI reference model
 - Protocol Data Units of higher levels: “messages”
- “Checking” those messages:
 - **Verification:** If a specification is correct according to the design. Prior to the implementation.
 - **Validation:** Check if customer expectations fulfilled
 - **Conformance check:** Check if an implementation matches the underlying specification



Testing methods for software (e.g. source code)

- Architecture: Test system around System Under Test (SUT)
 - Stimulation via input parameters
 - Check of states or return values
 - E.g. Unit Tests
- Coverage criteria
 - E.g. check program execution paths



Testing network protocols

- Fuzzing: Generate random input/network data
 - Conformance check
 - Replace other protocol layers with test system (upper tester, lower tester)
 - Run subsequent test cases...
- Difficult for already running systems without test interfaces
- Demand for diagnosis after commissioning

Protocol specifications given in different formats

Example: Generation frequency of V2X
status messages (CAMs) as plain text:

17

Final draft ETSI EN 302 637-2 V1.3.1 (2014-09)

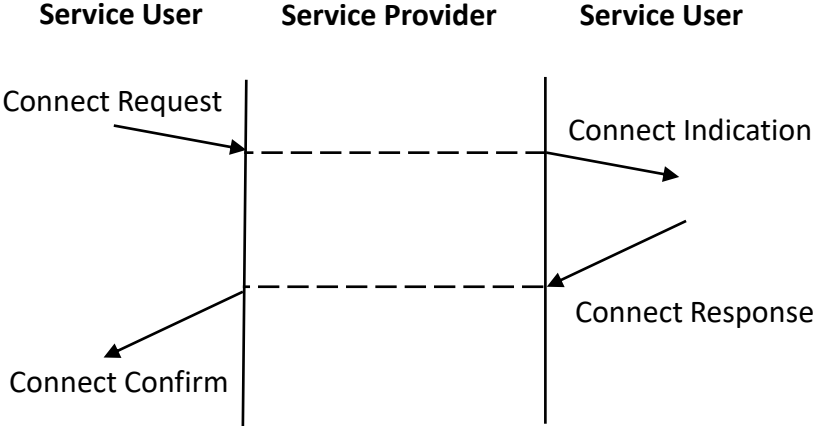
6.1.3 CAM generation frequency management for vehicle ITS-Ss

The CAM generation frequency is managed by the CA basic service; it defines the time interval between two consecutive CAM generations. Considering the requirements as specified in ETSI TS 101 539-1 [i.8], ETSI TS 101 539-2 [i.9] or ETSI TS 101 539-3 [i.10] the upper and lower limits of the transmission interval are set as follows:

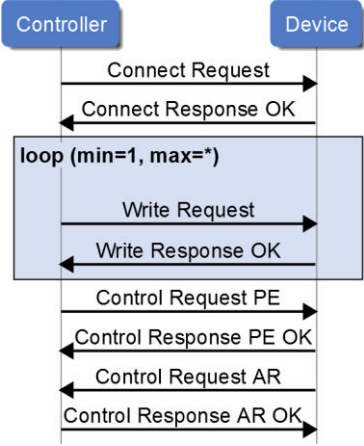
- The CAM generation interval shall not be inferior to $T_GenCamMin = 100$ ms. This corresponds to the CAM generation rate of 10 Hz.
- The CAM generation interval shall not be superior to $T_GenCamMax = 1\ 000$ ms. This corresponds to the CAM generation rate of 1 Hz.

Formal graphical descriptions for network protocols (1)

Time Flow Charts

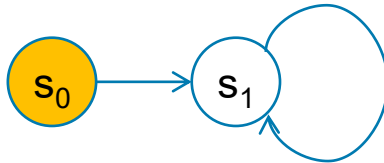


Sequence Charts

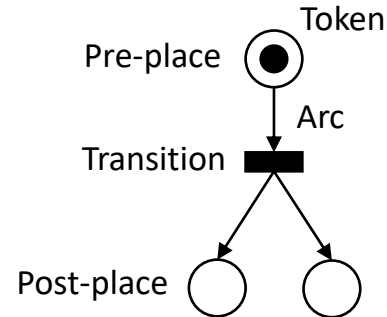


Formal graphical descriptions for network protocols (2)

Finite State Machines



Petri nets



*Aim: Check requirements
and errors at the same
time (like parallel test
cases, but not all have to
be executed) → diagnosis*

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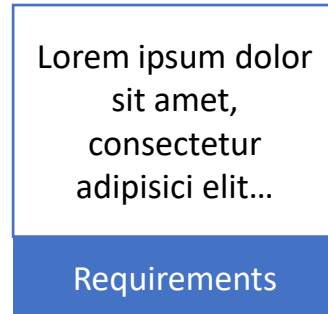
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Approach

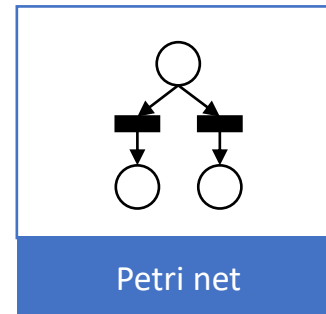
Approach: Using a Petri net to compare network messages against requirements



↓ *Continuously,
at runtime*

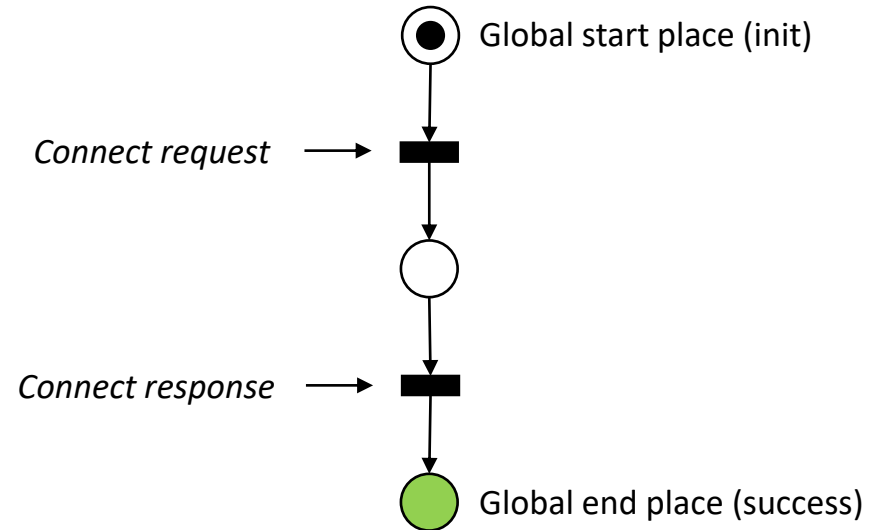


*Once,
before-
hand*



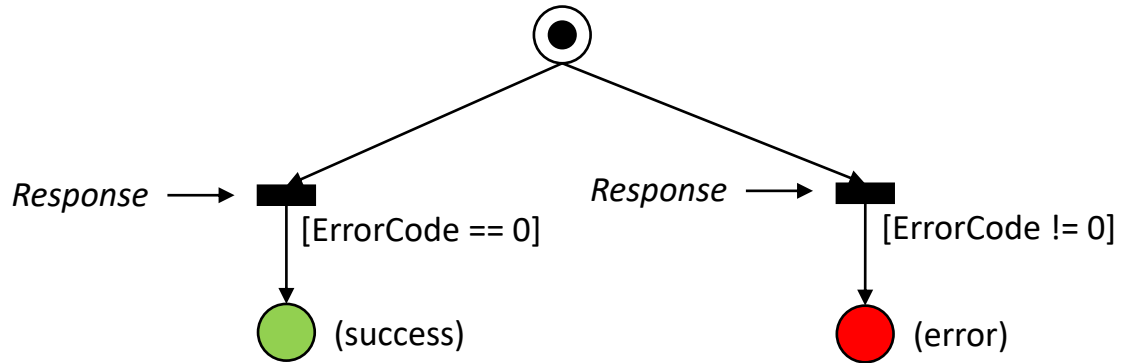
Case 1: Check a sequence of messages

Example: *“A connect request is followed by a connect response.”*

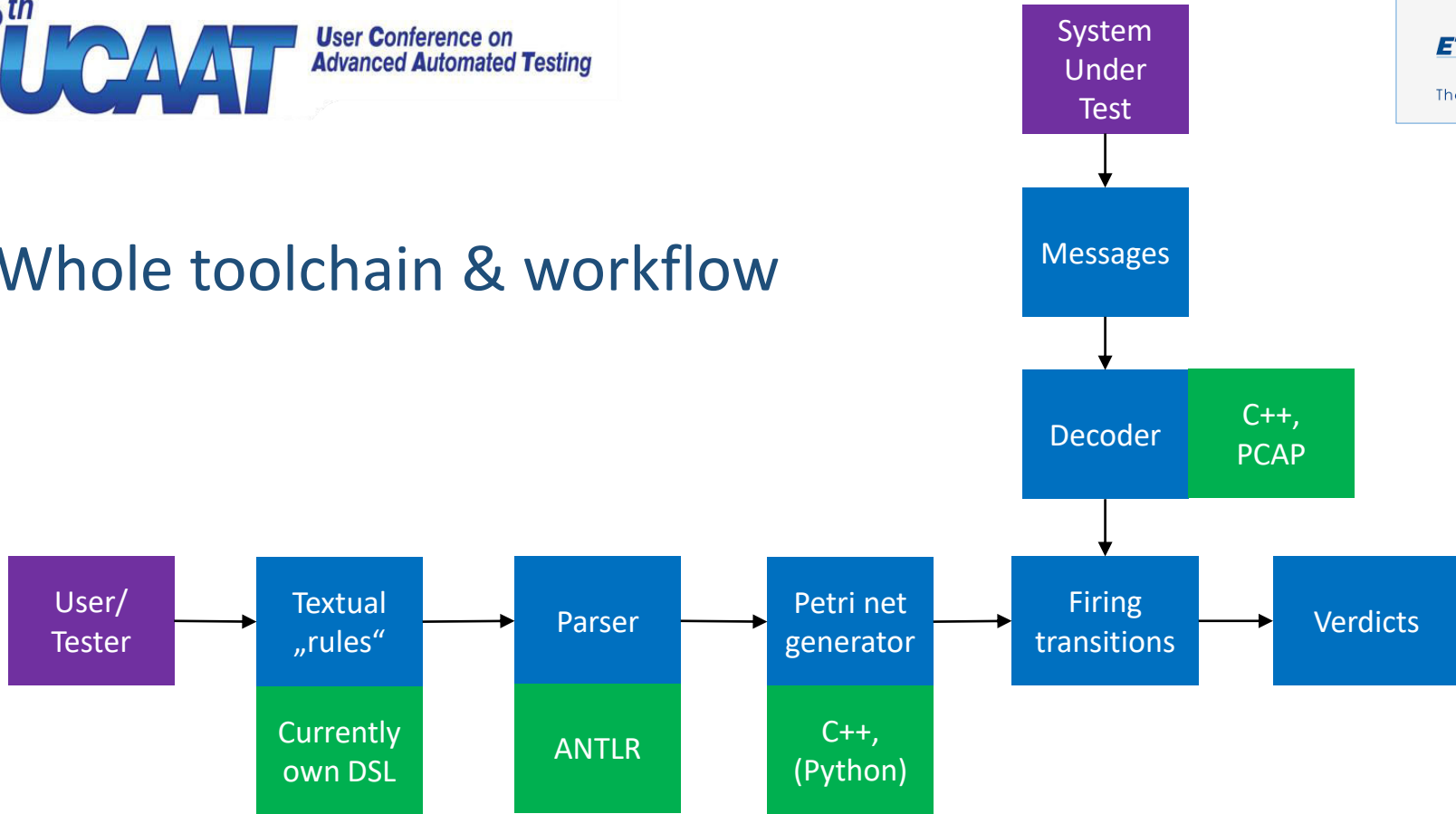


Case 2: Check parameter values within messages

Example: *“The ErrorCode of the response must be 0.”*



Whole toolchain & workflow



Creation of structures via subnets

- Structures for control flow, e.g. from UML Sequence Diagrams
- Considered most important:
 - Alternatives (“alt”)
 - Parallels (“par”)
 - Loops (“loop”)
 - Errors (“not”)
- Start and end places as interfaces between structures

Description of net creation with Python

Text

„A net N consists of places P , transitions T and flow relations F .“

Mathematical

$$N = (P; T; F)$$

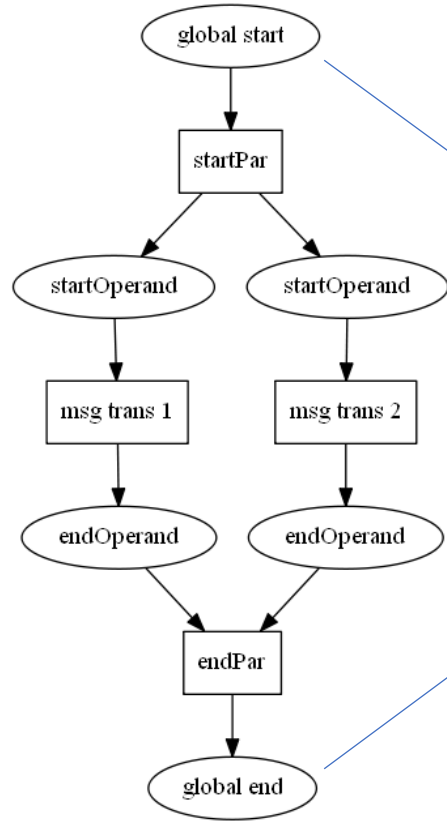
Python

```
class Petrinet :  
    def __init__(self):  
        self.places = []  
        self.transitions = []  
        self.arcs = []
```

```
def createPar(self, interfaces, operandCount):
    startTrans = self.petrinet.addTransition()
    self.petrinet.addArc(interfaces.getStartPlace(), startTrans)
    endTrans = self.petrinet.addTransition()
    self.petrinet.addArc(endTrans, interfaces.getEndPlace())
    operands = []

    for i in range(0, operandCount):
        operandStartPlace = self.petrinet.addPlace()
        self.petrinet.addArc(startTrans, operandStartPlace)
        operandEndPlace = self.petrinet.addPlace()
        self.petrinet.addArc(operandEndPlace, endTrans)
        operandInterfaces = NetInterfaces(operandStartPlace, operandEndPlace)
        operands.append(operandInterfaces)

    return operands
```



possible interfaces to other structures

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Use Case

Use Case: Vehicle-to-X communication (V2X)

- Vehicles send out status messages periodically (Cooperative Awareness Messages, CAM)
- Monitoring modules shall capture and check messages according to user defined rules



First prototype



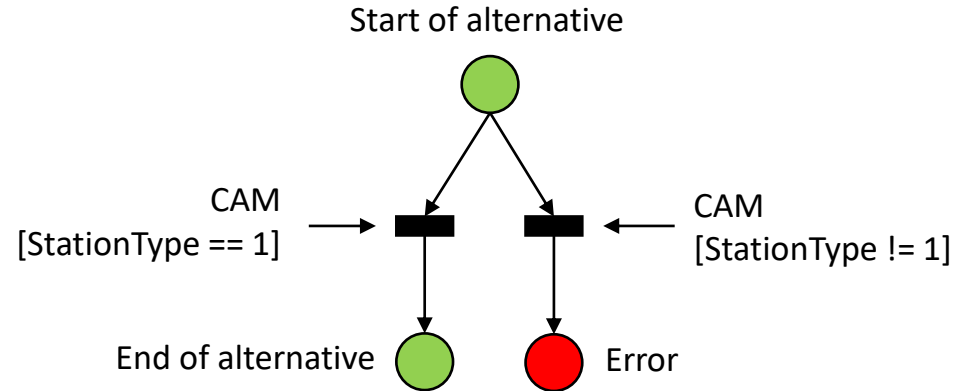
New version

User-selected requirements for CAM payload

- User defined: StationType == 11 (Tram)
- From CAM protocol specification: $1 \text{ Hz} \leq f \leq 10 \text{ Hz}$

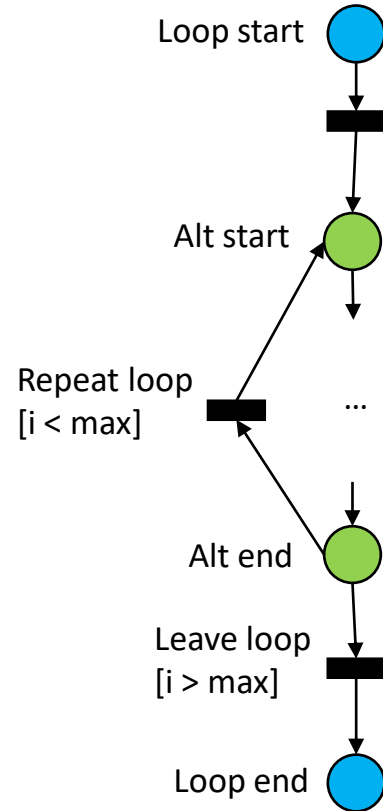
Check the vehicle role (1)

“Every CAM shall have a station type of 1.”



Check the vehicle role (2)

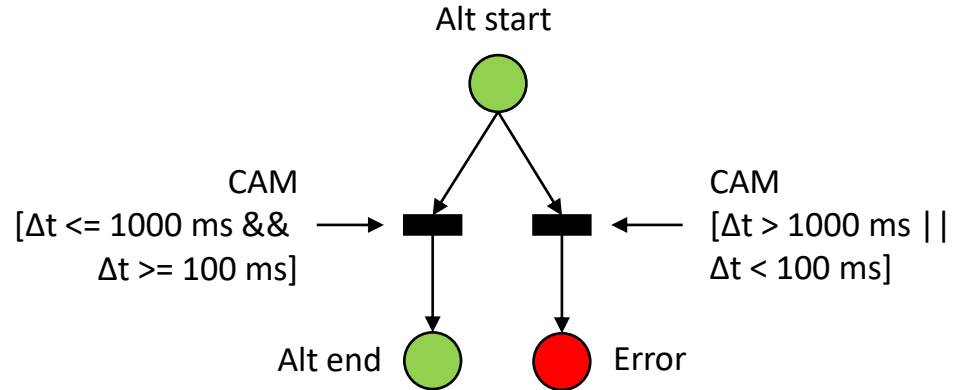
“Every CAM shall have a station type of 1.”



Check the message interval (1)

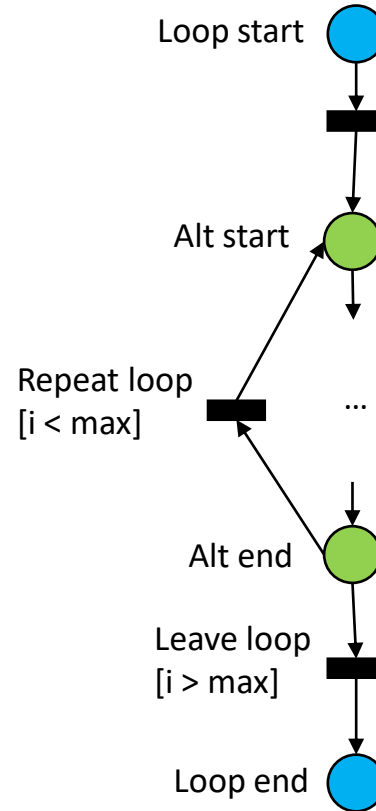
“The transmit frequency shall always be between 1 Hz and 10 Hz.”

$$\Delta t = t_{CAM(n)} - t_{CAM(n-1)}$$

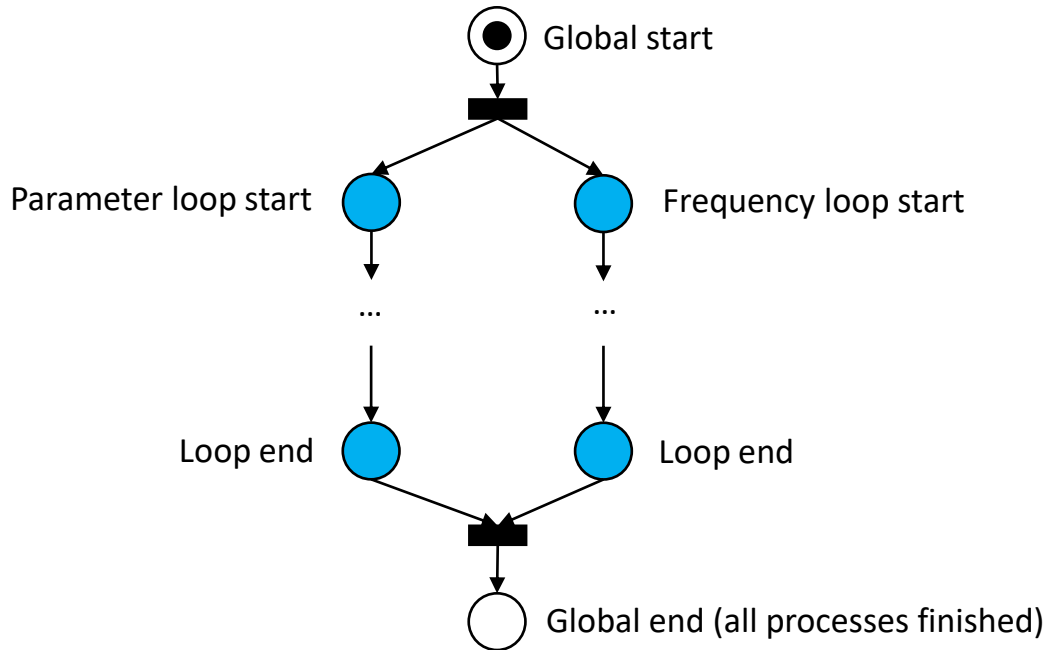


Check the message interval (2)

“The transmit frequency shall always be between 1 Hz and 10 Hz.”



Check parameter and frequency



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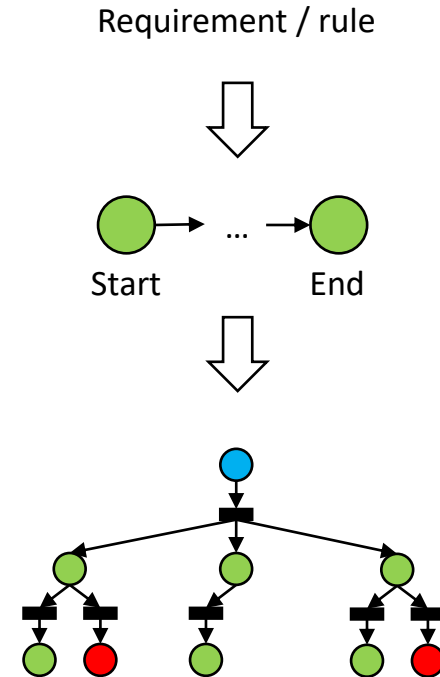
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Summary

Summary

- Check several requirements and detect errors at the same time → Diagnosis
- User-selected requirements as “rules”
- Petri subnets with interface places
- Connect subnets
- React to decoded messages (move tokens), create verdicts



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Thank you for your kind attention

Tim Ruß

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(Backup)

```
import <denm_cancelation.components> as stations

Rule {

    name: "DENM Cancelation";
    description: "Abkündigung einer DENM prüfen"

    Declaration {
        Signal {
            name: "V2X_DENM";
            use DENM.causeCode as cause;
        }
    }

    sequence {
        Loop [3] {
            Message CyclistWarning(from == rsu and to == car1);
            Message CyclistWarning(from == rsu and to == Any);
        }
        Message CyclistWarning(from == rsu and to == Any and canceled == true);
    }
}
```